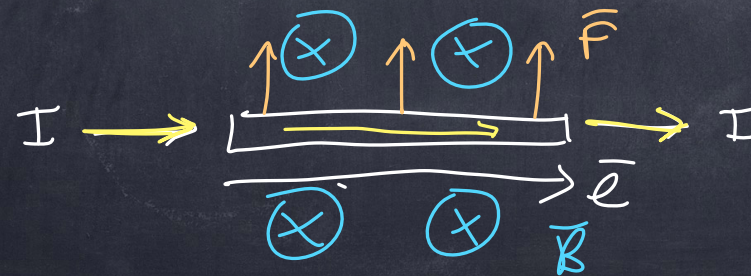


PHY 117 HS2024

Week 10, Lecture 2
Nov. 20th, 2024
Prof. Ben Kilminster

Yesterday:



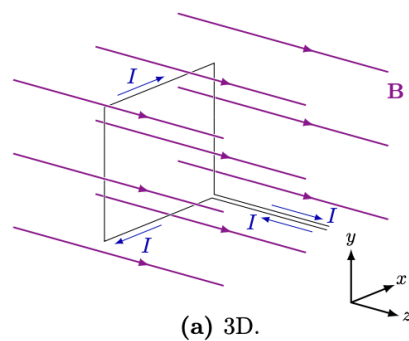
$$F = BIl$$

↑
length of wire

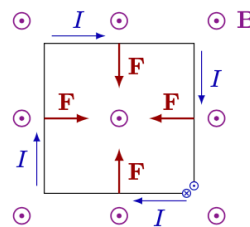
what about a loop of current?

80

CHAPTER 7. MAGNETISM



(a) 3D.



(b) 2D in xy plane.

Figure 7.9: Rectangular current loop in an external, uniform magnetic field $\mathbf{B} = B\hat{z}$.

No net force,
no net torque

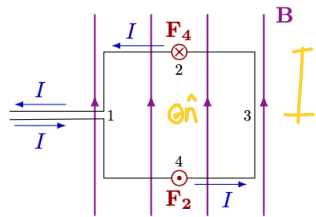


Figure 7.10: Rectangular current loop in an external magnetic field \mathbf{B} .

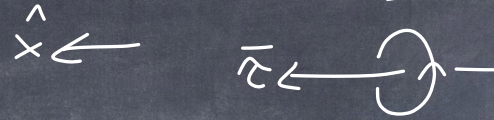
Here, there is torque
 $\tau = \vec{r} \times \mathbf{F}$

Segments 1 + 3 are parallel to \vec{B} ,
so no force, no torque.

Segment 2: $F_2 = BIl_2$, $\tau_2 = \frac{l_1}{2} BIl_2 \hat{x}$
segment 4: $F_4 = BIl_2$, $\tau_4 = \frac{l_1}{2} BIl_2 \hat{x}$

The loop will twist from the torque
(Notice \hat{n} of loop $\perp \vec{B}$)

$$\text{Total torque} = \vec{\tau}_2 + \vec{\tau}_1 = \frac{l_1}{2} B I l_2 + \frac{l_1}{2} B I l_2 = \pm (l_1 l_2) B = \pm A B \hat{n}$$

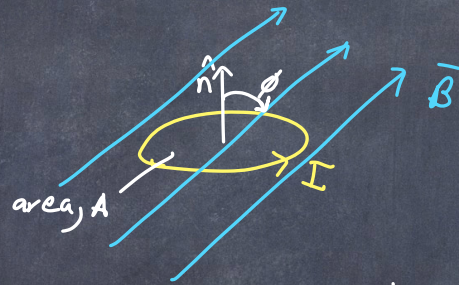


↑
area

If loop \hat{n} is at an angle with respect to \vec{B} ,

then in general

$$\vec{\tau} = I A \hat{n} \times \vec{B} = I A B \sin \theta$$



θ : is the angle from \hat{n} to \vec{B}

\hat{n} : normal direction \perp to the plane of the loop.

Torque is always in the direction that aligns $\hat{n} \rightarrow \vec{B}$

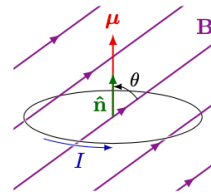
We can define the magnetic moment of the loop as $\vec{\mu} = I A$

and the $\vec{\mu}$ vector

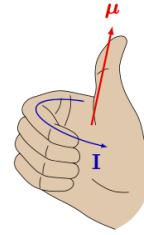
$$\vec{\mu} = (I A) \hat{n}$$

then

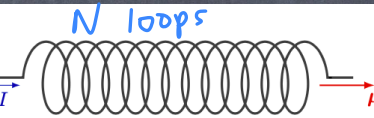
$$\vec{\tau} = \vec{\mu} \times \vec{B}$$



(a) Magnetic moment of a current loop in a uniform magnetic field.



(b) Right-hand rule for the magnetic moment of a current loop.

Figure 7.12: Magnetic moment of a solenoid with N windings.

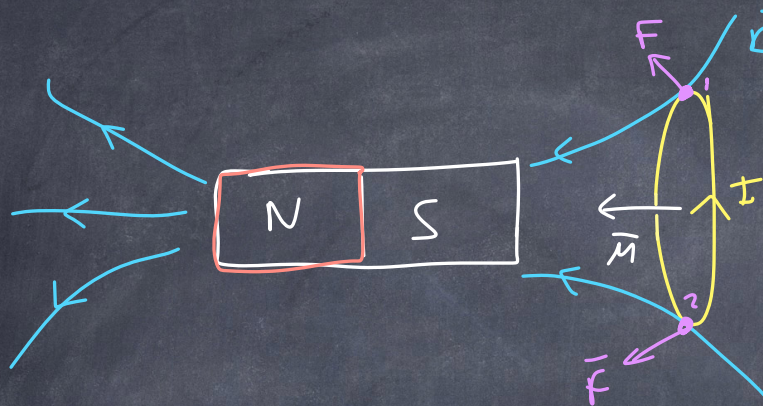
$$\vec{M} = N(IA) \hat{n}$$

The potential energy of a current loop in \vec{B} -field is

$$U = -\vec{M} \cdot \vec{B} + \text{constant}$$

we set the constant so that when \vec{M} is \parallel to \vec{B} , then $U = 0$.

What if the magnetic field is non-uniform?



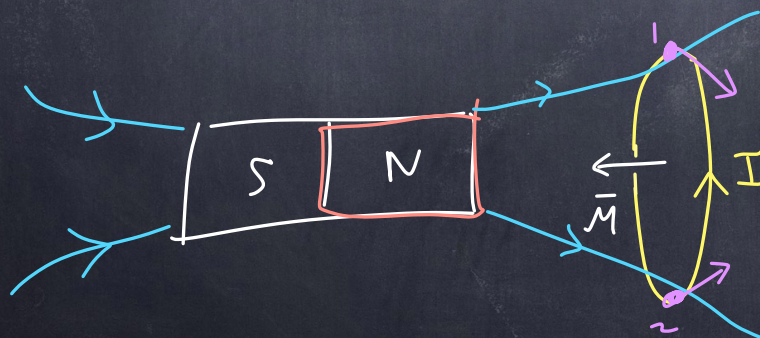
Consider 2 opposite points

$$1: \vec{F}_1 = q\vec{v} \times \vec{B} \quad \left. \begin{array}{l} \vec{v} = \otimes \\ \vec{B} = \leftarrow \end{array} \right\} \vec{F}: \nearrow$$

$$2: \vec{F}_2: \left. \begin{array}{l} \vec{v} = \circ \\ \vec{B} = \leftarrow \end{array} \right\} \vec{F}: \nwarrow$$

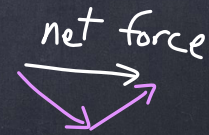
The net force is towards the magnet.

 (vertical components cancel out)



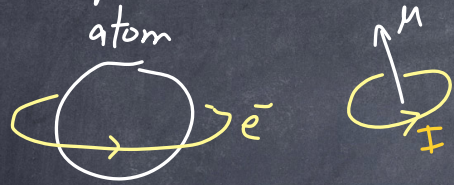
$$1: \vec{F}: \left. \begin{array}{l} \vec{v} = \otimes \\ \vec{B} = \rightarrow \end{array} \right\} \vec{F} = \searrow$$

$$2: \vec{F}: \left. \begin{array}{l} \vec{v} = \circ \\ \vec{B} = \searrow \end{array} \right\} \vec{F} = \nearrow$$

 net force

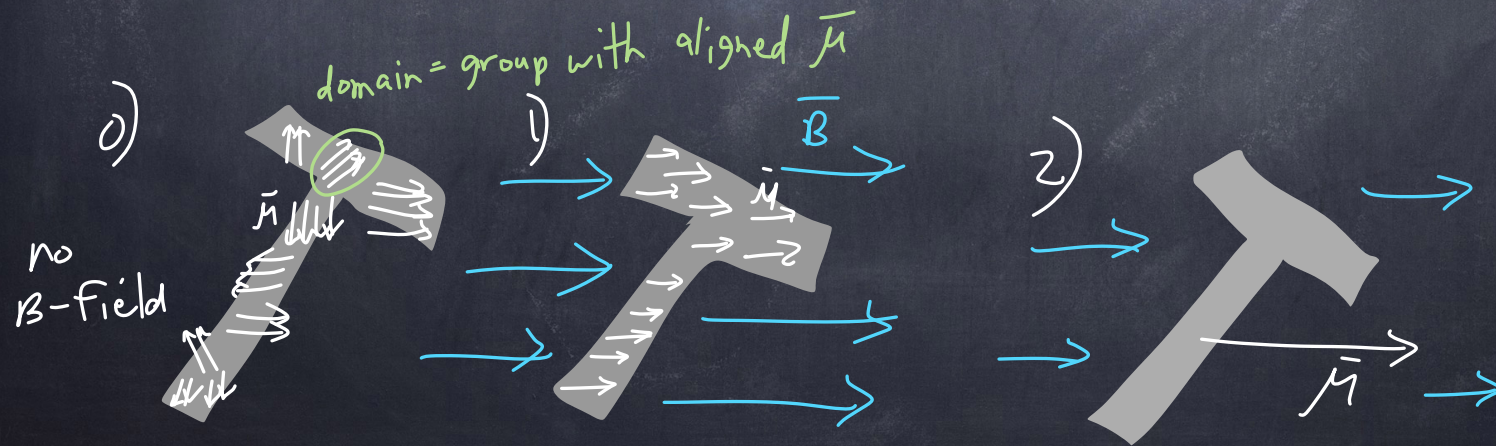
The net force is away from the magnet

Electrons and atoms can be thought of as spinning electric charges.

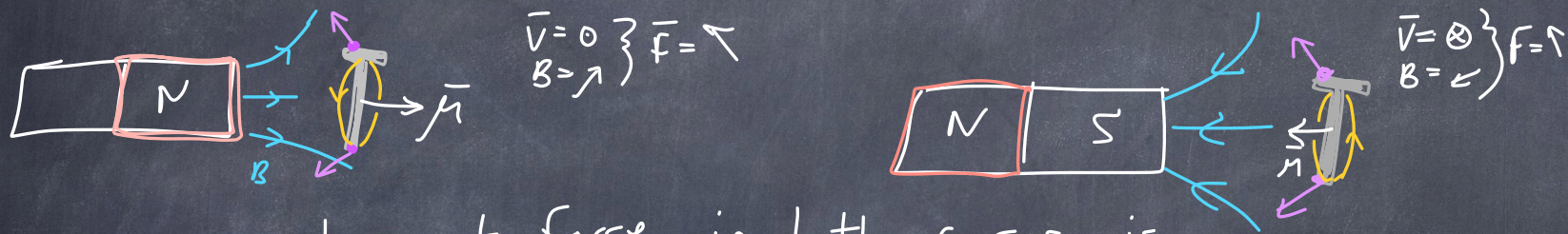


Each atom has a magnetic moment, $\vec{\mu}$.

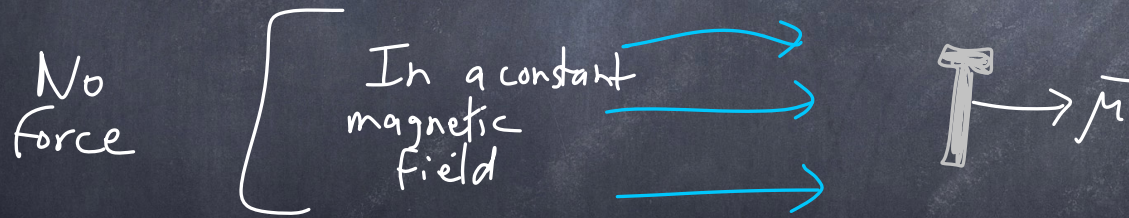
This helps us understand why an unmagnetized nail is attracted to a magnet, both the N + S side. This happens in a few steps:



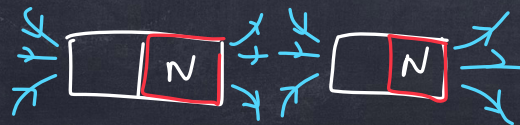
Why is nail attracted to N + S poles of magnet?
 First, nail is magnetized in direction of field.
 Second, divergent field causes a force of attraction.



The net force in both cases is toward the magnet.



This is also why two magnets attract



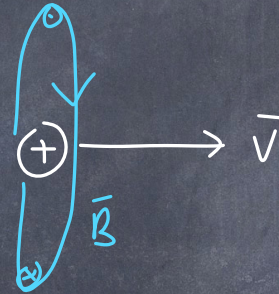
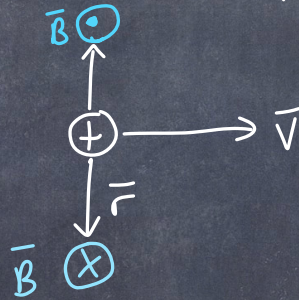
So far, we know:

$$\vec{F}_B = q\vec{v} \times \vec{B} \quad \vec{F} \perp \vec{v}, \vec{B}$$

$$\vec{F}_B = I\vec{\ell} \times \vec{B} \quad \vec{F} \perp \vec{\ell}, \vec{B}$$

Now: A moving charge $\oplus \rightarrow \vec{v}$
generates its own magnetic field.

The direction of \vec{B} is $\vec{v} \times \vec{r}$



The magnetic field loops around the direction of motion.

The magnitude of B decreases like $\frac{1}{r^2}$

$$\vec{B} = \frac{\mu_0}{4\pi} q \frac{\vec{v} \times \hat{r}}{r^2}$$

$[T]$ $\left[\frac{T \cdot m}{A}\right]$ $\frac{[C] \left[\frac{m}{s}\right]}{[m^2]}$

\vec{B} caused by a moving charge.
 μ_0 : permeability of free space
 vacuum

$$\mu_0 = 4\pi \cdot 10^{-7} \frac{T \cdot m}{A}$$

$$[A] = \left[\frac{C}{s}\right]$$

For a current, the form is

$$d\vec{B} = \frac{\mu_0}{4\pi} I \frac{d\vec{\ell} \times \hat{r}}{r^2}$$

Biot-Savart law:
 Integrate to solve for
 any shaped wire in
 a B-field.

we won't do any exercises
 with Biot-Savart law.

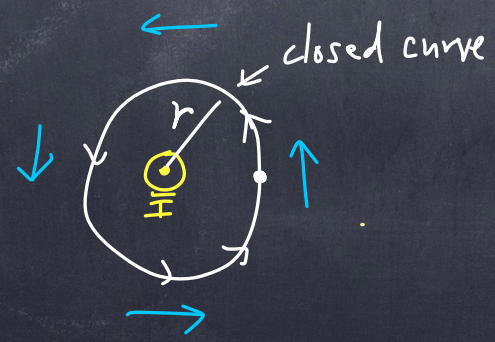
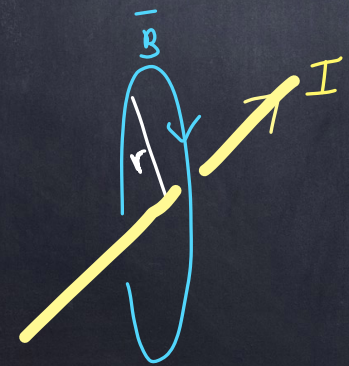
$$\vec{B} = \int \frac{\mu_0}{4\pi} I \frac{d\vec{\ell} \times \hat{r}}{r^2}$$

However, for simple configurations of current, there is an easier way. (like Gauss' Law)

Ampere's Law

$$\oint_{\text{closed curve}} \vec{B} \cdot d\vec{\ell} = \mu_0 I_c$$

I_c : current passing through the closed curve.



we pick a curve where $\vec{B} \parallel \vec{\ell}$

$$\oint_C \vec{B} \cdot d\vec{\ell} = \mu_0 I_c$$

$$B \oint_C d\ell = \mu_0 I$$

↓

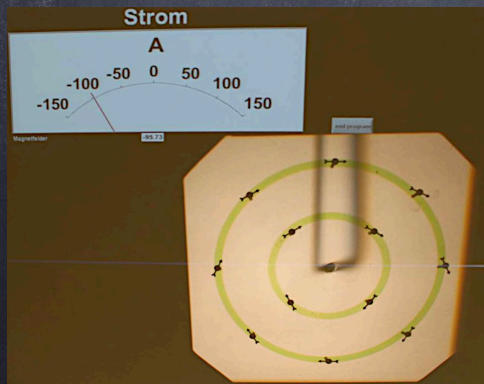
$$B(2\pi r) = \mu_0 I$$

$$B = \frac{\mu_0 I}{2\pi r}$$

$\oint_C d\ell = 2\pi r$, the circumference of a circle

we see here:

$$B \propto \frac{1}{r} \quad B \propto I$$



Using Ampere's law on a solenoid:

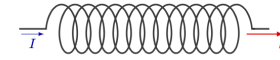
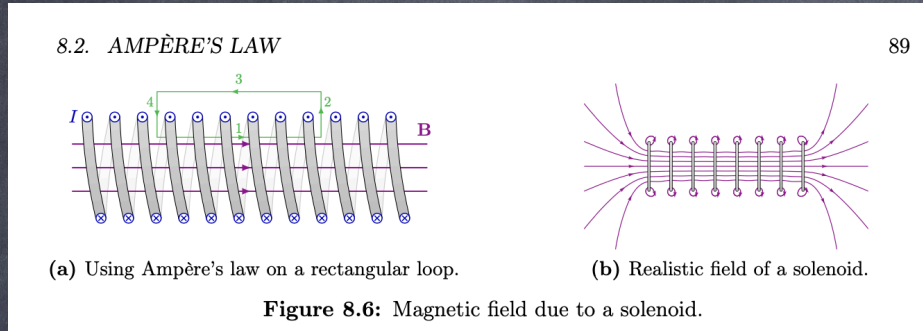


Figure 7.12: Magnetic moment of a solenoid with N windings.



sides 1 & 3 have
length, x

$$n = \frac{N \text{ loops}}{\text{length}}$$

$$I_c = (nx) I$$

Then $\oint \vec{B} \cdot d\vec{\ell} = \mu_0 I_c$

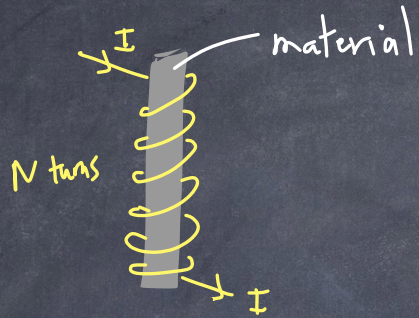
$$\underbrace{Bx}_{\vec{B} \parallel d\vec{\ell}} + \underbrace{0}_{\vec{B} \perp d\vec{\ell}} + \underbrace{0}_{\vec{B} \approx 0} + \underbrace{0}_{\vec{B} \perp d\vec{\ell}} = \mu_0 n x I$$

$$Bx = \mu_0 n x I$$

$$B = \mu_0 n I = \mu_0 \frac{N}{l} I$$

magnetic field
in a hollow
Solenoid.

If there is a material inside,

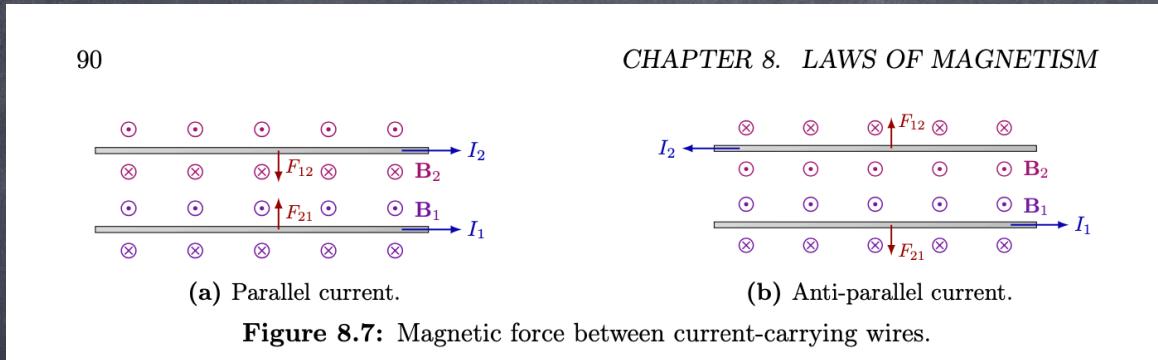


$$B = \mu n I \quad \text{where } \mu = \mu_0 k$$

Here, k is the relative permeability

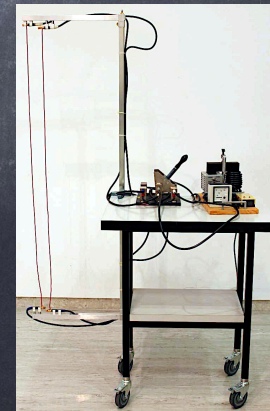
<u>material</u>	<u>$k \left(\frac{\mu}{\mu_0} \right)$</u>
air	1.000 000 37
water	0.999 99 2
Copper	0.999 99 4
pure iron (99.95%)	2 00 000
iron 99.8%	5 000

A current I_1 produce a magnetic field $B_1 = \frac{\mu_0 I_1}{2\pi r}$
 Another current I_2 will feel a force from B_1 , $F = B_1 I_2 l$



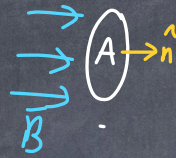
$$F_{12} = \frac{\mu_0 I_1 I_2 l}{2\pi r} \quad \text{also } \vec{F}_{12} = -\vec{F}_{21}$$

attractive or repulsive:



Magnetic flux:

For a loop \perp to \vec{B} -field



we can quantify the \vec{B} -field by

$$\Phi_m = BA$$

A: area

where Φ_m is known as the magnetic flux

If \hat{n} is not \parallel to \vec{B} , then

$$\Phi_m = \vec{B} \cdot \hat{n} A = BA \cos \theta$$



units are Weber:

$$1 [\text{Wb}] = 1 [\text{T} \cdot \text{m}^2]$$

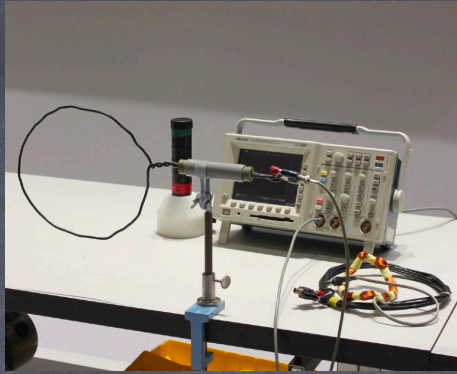
If magnetic flux changes, an electric field will be produced. The electric field produces an \mathcal{E} mf

$$\mathcal{E} = \oint_C \vec{E} \cdot d\vec{\ell} = - \frac{d\Phi_m}{dt}$$

↑
Voltage supplied

Known as Faraday's Law.

$$\text{Notice } [V] = \left[\frac{\text{Wb}}{\text{s}} \right]$$



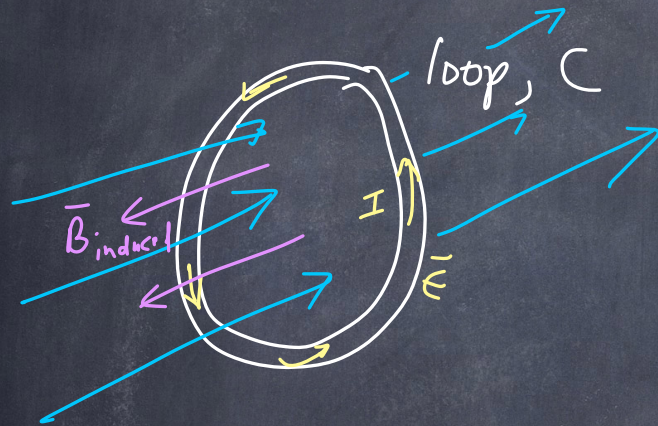
$\Phi_m = \vec{B} \cdot \hat{n} A$
can be changed by
changing B or A or \hat{n} !

IF magnetic flux changes, an electric field will be produced. The electric field produces an \mathcal{E}_{mf} . This electric field means that a current is produced. But a current produces a magnetic field! what?

Lenz's Law: "The induced \mathcal{E}_{mf} and induced current are in such a direction so as to oppose the change that produces them."

This means:

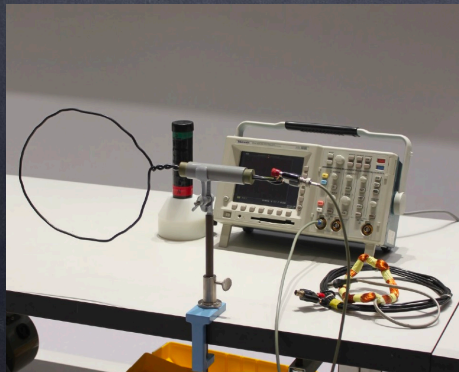
1) A moving magnet induces magnets in the opposite direction.



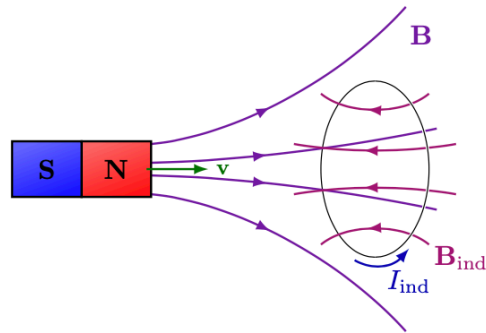
B is + increasing

If we increase \vec{B} ,
 I is produced.

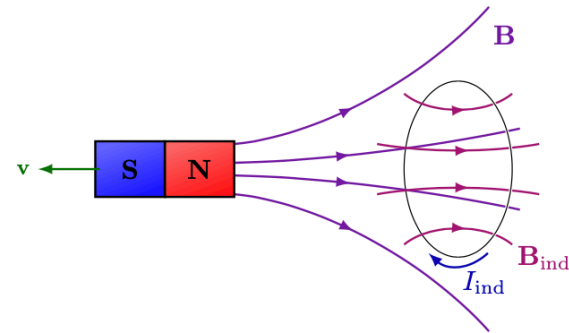
(But in opposite direction)



\vec{B}_{induced} opposes changes in \vec{B}



(a) Field moving toward the loop.

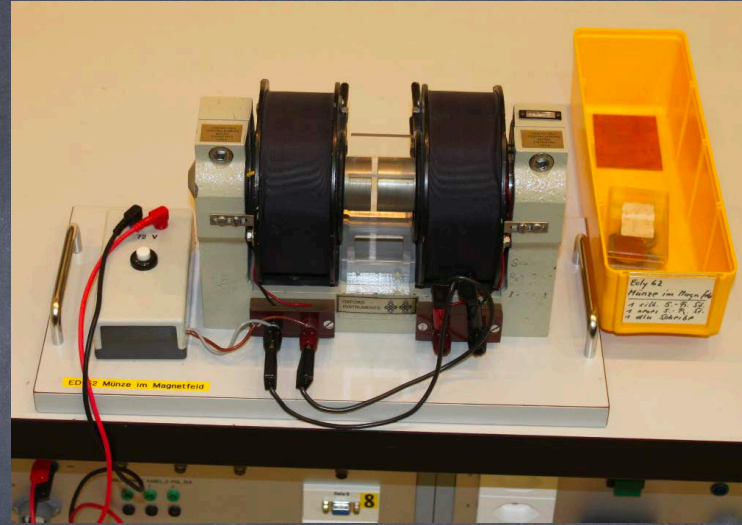


(b) Field moving away from the loop.

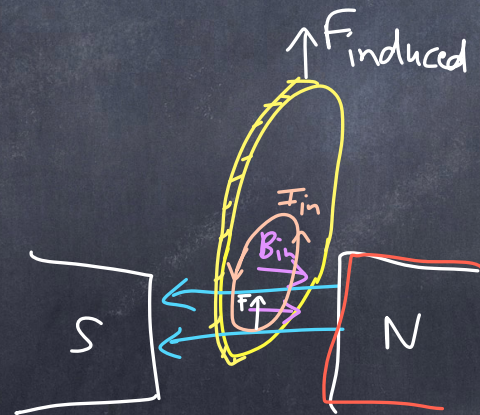
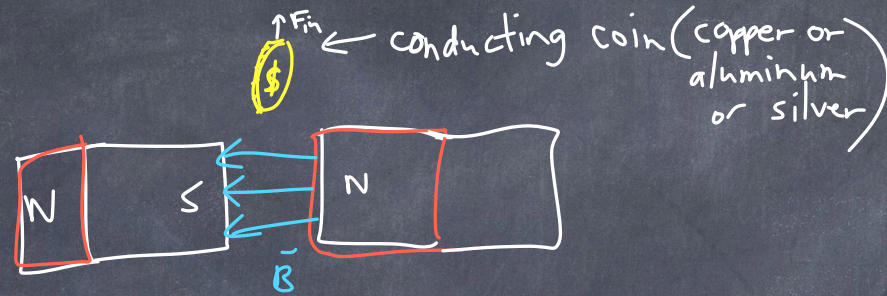
Figure 8.8: The magnetic field \vec{B} of a moving bar magnet will induce a current I_{ind} in a conducting loop and therefore a magnetic field \vec{B}_{ind} .

If \vec{B} increases, \vec{B}_{ind} is opposite \vec{B}

If \vec{B} decreases, \vec{B}_{ind} is in the same direction as \vec{B}



Dropping a conductor
through a magnet.



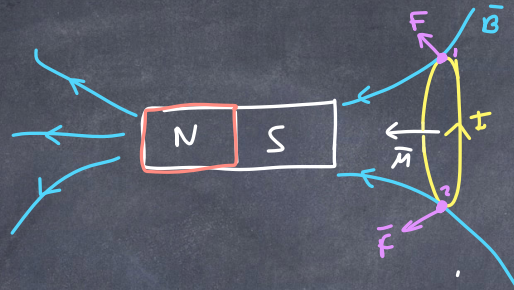
we call induced currents
"Eddy currents"



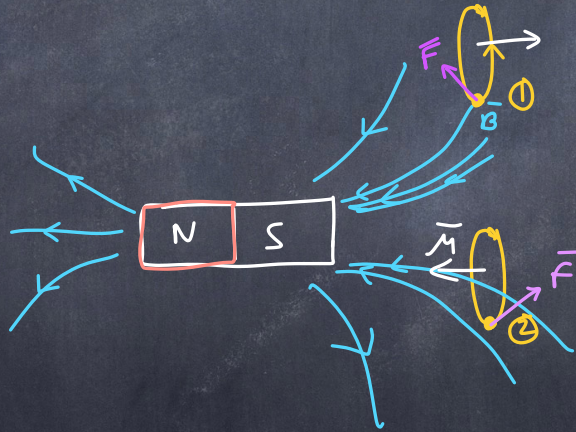
cuts out
prevents
Eddy currents

What if the magnetic field is non-uniform?

Remember!



In this case, the loop falls through the non-uniform field.



As it falls, the B-field gets bigger, so the induced current opposes the external B-field

• ①: $\vec{v} = \otimes$ $\vec{B} = \leftarrow$ $\vec{F} = \uparrow$

Below, the induced magnetic field is in the same direction, resulting in an upward force

• ②: $\vec{v} = \otimes$ $\vec{B} = \leftarrow$: $\vec{F} = \uparrow$

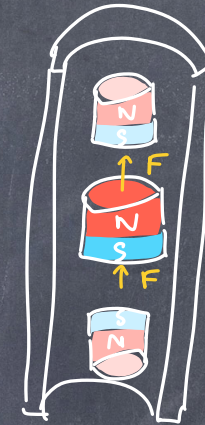
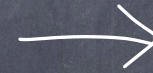
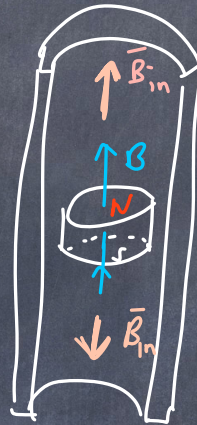
Force has up component in both cases
(keep in mind there are two magnets so horizontal force cancels out)



As magnet falls:

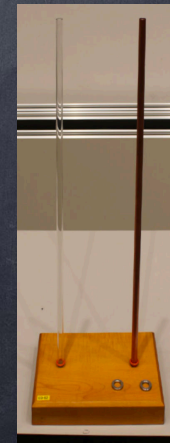
\vec{B} decreases above magnet

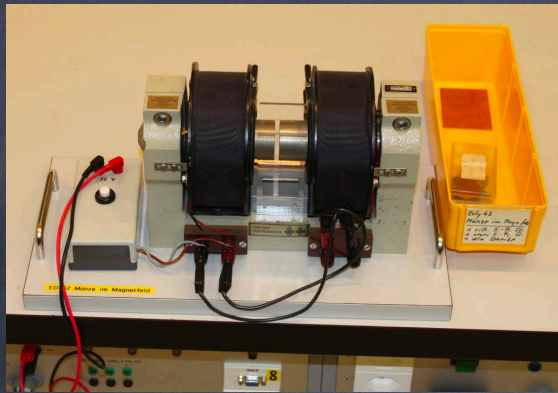
\vec{B}_{in} is same direction as \vec{B}



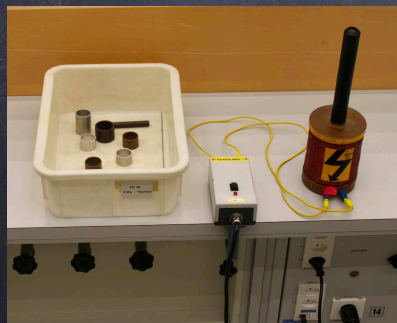
\vec{B} increases below the magnet

$\vec{B}_{induced}$ opposite of \vec{B}





Dropping a conductor
in a magnet



turning a conductor into
an opposing magnet

cutout
prevents
Eddy currents

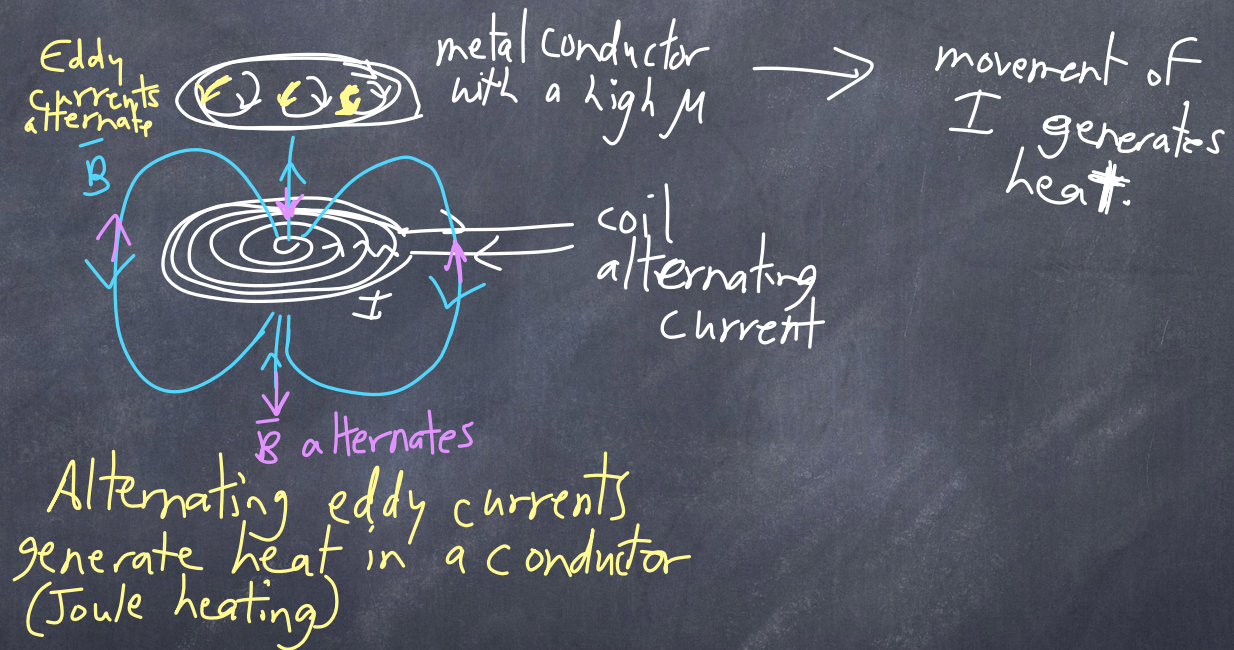


dropping magnet in
a conductor

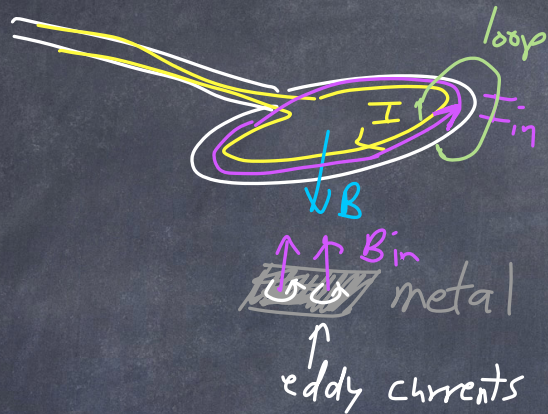
Summary of magnetic field concepts:

- 1) A moving electric charge may feel a force from a magnetic field.
- 2) A moving electric charge generates its own magnetic field. (A changing electric field produces a magnetic field.)
- 3) A changing magnetic field generates electric currents that produce an opposing magnetic field.

Induction stove uses Eddy currents?

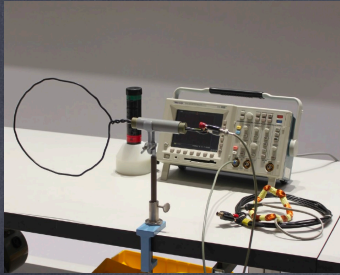


Metal detector uses Eddy currents



I_{in} is generated
in opposite direction,
tends to decrease
current in metal
detector.

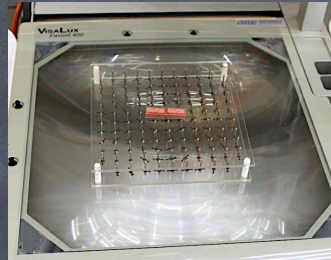
Metal detector searches
for currents in
opposite directions.



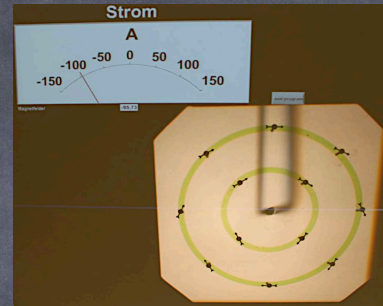
ED48



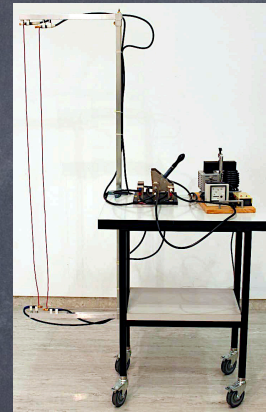
ED63



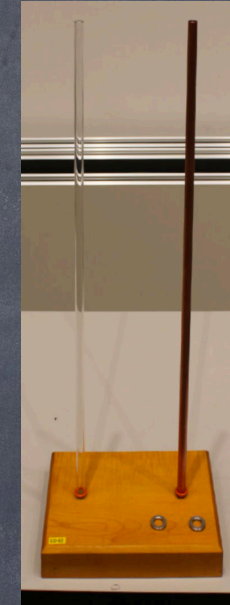
ED6



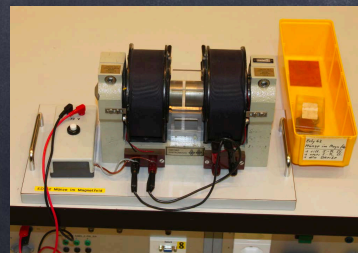
ED10



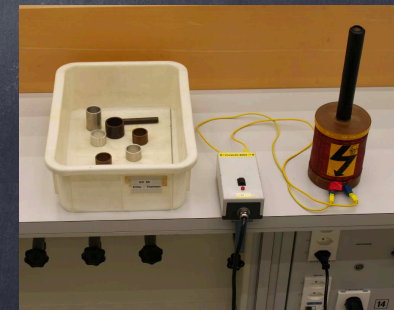
ED14



ED62



ED61



ED66